

BAPATLA ENGINEERING COLLEGE:: BAPATLA

(Autonomous)

| | | NU | MER | | | | | | | | | D CA MA02 | | JLUS | | | |
|--|---------------------------------|---------------------------------|------------------------|-------------------------|-------------------------|------------------------------------|--------------------|-----------------------------------|------------------------|--------------------------|--------------------------|--------------------------|------------------------|-------------------------------|----------------------------------|---------------------|--------------|
| Lectures | | : | 2 Ho | | | | utor | | : | | | r/Wee | | Practic | al | : | 0 |
| CIE Marl | ζS | : | 30 | | | S | SEE N | Mark | s : | 7 | 0 | | | Credits | 5 | : | 3 |
| Pre-Req | uisite: | Non | e | | | | | | | | | | | | | | |
| Course (| Objecti | ives: | Stude | ents v | will le | earn | how | to | | | | | | | | | |
| | | - | gebrai meth | | ansce | nder | ntal a | and | syste | m o | f line | ear e | quatio | ons wi | th th | e h | elp c |
| \triangleright | are n | ot ap | | ble a | nd so | olve t | he fi | rst of | rder | ordin | ary d | liffere | | erever r equatio | | | |
| \triangleright | | | | | | | | | | | | | | and vo | | | |
| \blacktriangleright | Evalı appli | | | ne, s | surfa | ce ai | nd vo | olum | e int | egra | ls an | d lea | rn th | eir inte | er-rela | atior | is an |
| CO-2 CO-3 CO-4 | condi Findt integ Appl | ition. he a rals. y ve | irea a | ind v | volun gral | ne o theor | f pla rems | ine a | and 1 otain | three the | dim solu | ensio | nal f | v with t igures engined | using | g m | ultip |
| Mapping | of Cou | rse (| Dutcor | nes v | vith F | Progr | am C | Outco | mes | & Pr | ogran | n Spec | cific (| Outcom | es | | |
| | - | | | | | | 1 | <u>D's</u> | - | | | | | | PSO ⁹ | | _ |
| | 0)-1 | 1 3 | 2 | 3 2 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 2 | 1 | 2 3 | | 3 |
| |)-1)-2 | $\frac{3}{3}$ | 3 | 2 | - | - | - | - | - | - | - | - | 2 | - | $\frac{3}{3}$ | | - |
| | | 3 | 3 | 2 | - | - | - | - | _ | _ | - | - | 2 | _ | 2 | | _ |
| CO-3 CO-4 | | 3 | 3 | 2 | - | - | - | - | - | - | - | - | 2 | - | 3 | | - |
| | | | | | | | | | | | | | | I | | • | |
| Numeric equations deductior methods | s: Bise ns from of sol | ection n the utior | n me Newt n: Gau | thod, ton-R uss e | , Me Caphs climir | ns: I ethod son fo nation | of ormu n me | luctio false la; Se thod | e po olutio , Ga | sitior on of uss-J | n, Ne Elinea ordar | ewton ar sim 1 met | -Rap iultan hod, | hson n eous eo Factori | tran nethc quatic zatio | scen od; ons; | Usef Dire |
| Iterative [Sections | | | | | | | | | | l, Gai | uss-S | eidel | iterat | ive met | hod. | | |

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| UNIT-2 | | | | | | | |
|---|---|---|--|--|--|--|--|
| Finite differe | ences and Interpolation: Finite differences: Forward difference | es, Backward | | | | | |
| differences; Newton's interpolation formulae: Newton's forward interpolation formula, Newton's | | | | | | | |
| backward interpolation formula; Interpolation with unequal intervals; Lagrange's interpolation | | | | | | | |
| formula; Divided differences; Newton's divided difference formula; Numerical integration; | | | | | | | |
| Trapezoidal rule; Simpson's one-third rule; Simpson's three-eighth rule; Numerical solution of | | | | | | | |
| ODE's: Introduction; Picard's method; Euler's method; Runge-Kutta method. | | | | | | | |
| [Sections:29.1; 29.1-1; 29.1.2; 29.6; 29.9; 29.10; 29.11; 29.12; 30.4; 30.6; 30.7; 30.8; 32.1; 32.2; | | | | | | | |
| 32.4; 32.7]. | | | | | | | |
| | UNIT-3 | (12 Hours) | | | | | |
| Multiple Inte | grals: Double integrals; Change of order of integration; Double inte | grals in polar | | | | | |
| coordinates; Area enclosed by plane curves; Triple integrals; Volumes of solids: Volume as | | | | | | | |
| Triple integral, Change of variables. | | | | | | | |
| [Sections: 7.1; 7.2; 7.3; 7.4; 7.5; 7.6.2; 7.7.2]. | | | | | | | |
| | UNIT-4 | (12 Hours) | | | | | |
| . | | | | | | | |
| | us and its Applications: Scalar and vector point functions; Del app | | | | | | |
| | us and its Applications: Scalar and vector point functions; Del applies-Gradient: Definition, Directional derivative; Del applied to | | | | | | |
| point function | | vector point | | | | | |
| point function functions: Div | ns-Gradient: Definition, Directional derivative; Del applied to | vector point oss a surface; | | | | | |
| point function functions: Div | as-Gradient: Definition, Directional derivative; Del applied to vergence, Curl; Line integral; Surfaces: Surface integral, Flux acrossm in the plane (without proof); Stokes theorem (without proof); Gau | vector point oss a surface; | | | | | |
| point function functions: Div Green's theore theorem(witho [Sections: 8.4; | ns-Gradient: Definition, Directional derivative; Del applied to vergence, Curl; Line integral; Surfaces: Surface integral, Flux acro em in the plane (without proof); Stokes theorem (without proof); Gau ut proof). 8.5; 8.5.1; 8.5.3; 8.6; 8.11.1; 8.12.2; 8.12.3; 8.13; 8.14; 8.16] | vector point oss a surface; oss divergence | | | | | |
| point function functions: Div Green's theore theorem(witho [Sections: 8.4; | ns-Gradient: Definition, Directional derivative; Del applied to vergence, Curl; Line integral; Surfaces: Surface integral, Flux acro em in the plane (without proof); Stokes theorem (without proof); Gau ut proof). | vector point oss a surface; oss divergence | | | | | |
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| point function functions: Div Green's theore theorem(witho [Sections: 8.4; Text Books : | Bas-Gradient: Definition, Directional derivative; Del applied to vergence, Curl; Line integral; Surfaces: Surface integral, Flux acrossment in the plane (without proof); Stokes theorem (without proof); Gau ut proof). 8.5; 8.5.1; 8.5.3; 8.6; 8.11.1; 8.12.2; 8.12.3; 8.13; 8.14; 8.16] B.S.Grewal, "Higher Engineering Mathematics", 44thedition, Khan 2017. [1] Erwin Kreyszig, "Advanced Engineering Mathematics", 9th | vector point oss a surface; oss divergence na publishers, edition, John | | | | | |